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## LETTER TO THE EDITOR

# Kinetic representation of discrete integrable systems 

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Abstract. The basic variables in discrete Lax equations can be represented as moments of the one-particle distribution function satisfying certain Vlasov-type kinetic dynamics. These kinetic equations are Hamiltonian, and the representation map is canonical.

In this letter we construct a hierarchy of kinetic equations which produces the basic hierarchy of discrete Lax equations. The latter has the form [1, 2]:

$$
\begin{align*}
& L_{, r}=\left[\left(L^{m}\right)_{+}, L\right] \quad m \in \mathbb{Z}_{+}  \tag{1}\\
& L=\zeta+\sum_{i=0}^{\infty} a_{i} \zeta^{-i} \tag{2}
\end{align*}
$$

where the $a_{i}$ can be thought of as functions of either $n \in \mathbb{Z}$ or $x \in \mathbb{R}$; in either case, the commutation rule of $\zeta$ and the $a$ is

$$
\begin{equation*}
\zeta^{\prime} a=\Delta^{\prime}(a) \zeta^{\prime} \quad l \in \mathbb{Z} \tag{3}
\end{equation*}
$$

where $\left[\Delta^{\prime}(a)\right](n):=a(n+l)$ and $\left[\Delta^{\prime}(a)\right](x):=a(x+l \varepsilon), \varepsilon$ being a (small) formal parameter. Thus, $\Delta$ acts on functions as dual to the argument shift, and $\zeta$ is the operator version of $\Delta$. The additional notation employed in (1) is

$$
\begin{align*}
& \left(\sum \varphi_{l} \zeta^{l}\right)_{+}:=\sum_{l \geqslant 0} \varphi_{l} \zeta^{l}  \tag{4}\\
& {[X, Y]:=X Y-Y X .} \tag{5}
\end{align*}
$$

For the first non-trivial case $m=1$, (1) becomes

$$
\begin{equation*}
a_{i, t}=(\Delta-1)\left(a_{i+1}\right)+a_{i}\left(1-\Delta^{-i}\right)\left(a_{0}\right) \tag{6}
\end{equation*}
$$

which turns, in the continuous limit $\varepsilon \rightarrow 0, \Delta=\exp (\varepsilon \delta / \partial x)$, into

$$
\begin{equation*}
a_{i, t}=a_{i+1, x}+\mathrm{i} a_{i} a_{0, x} \quad i \in \mathbb{Z}_{+} . \tag{7}
\end{equation*}
$$

Now, the infinite-component system (7) results, as is easy to verify, from the following dynamics for the one-particle distribution function $f=f(x, p, t)$ :

$$
\begin{align*}
f_{t} & =p f_{, x}-a_{0, x}(p f)_{, p}  \tag{8}\\
a_{n} & =\int_{-\infty}^{\infty} f p^{n} \mathrm{~d} p . \tag{9}
\end{align*}
$$

A similar kinetic representation can be given to the full dispersive system (6) and even to the whole hierarchy (1), as follows.

Set

$$
\begin{aligned}
& \left(\sum \varphi_{l} \zeta^{\prime}\right) \leqslant 0:=\sum_{l \leqslant 0} \varphi_{l} \zeta^{\prime} \\
& \operatorname{Smbl}\left(\sum \varphi_{1} \xi^{l}\right):=\sum \varphi_{l} p^{l}
\end{aligned}
$$

Property 1. For any $Q=\Sigma q_{r} r^{1}$, the system of motion equations

$$
\begin{equation*}
L_{, t}=\left[Q_{+}, L\right]_{\leqslant 0} \tag{10}
\end{equation*}
$$

results, via the moments map (9), from the single kinetic equation

$$
\begin{equation*}
f_{, t}=\left[\operatorname{Smbl}\left(Q_{+}\right), f\right]_{(1)} \tag{11}
\end{equation*}
$$

where

$$
\begin{equation*}
[X, Y]_{(1)}:=\sum_{r \geqslant 0} \frac{\varepsilon^{r}}{r!}\left[\left(p \partial_{p}\right)^{r}(X) \partial^{r}(Y)-\partial^{r}(X)\left(\partial_{p} p\right)^{r}(Y)\right] \quad \partial:=\partial / \partial x . \tag{12}
\end{equation*}
$$

Remark. $[X, Y]_{(1)} \neq-[Y, X]_{(1)}$.
Let $B=\left(B_{i j}\right)$ be the (first) Hamiltonian structure [1,2] of the hierarchy (1):

$$
\begin{equation*}
B_{i j}=\Delta^{j} a_{i+j}-a_{i+j} \Delta^{-i} . \tag{13}
\end{equation*}
$$

Thus, the motion equations with a Hamiltonian $H=H(a)$ are

$$
\begin{equation*}
a_{i,}=\sum\left(\Delta^{j} a_{i+j}-a_{i+j} \Delta^{-i}\right)\left(H_{j}\right) \quad H_{j}:=\delta H / \delta a_{j} . \tag{14}
\end{equation*}
$$

Property 2. For any Hamiltonian $H=H(f)$, consider the motion equation

$$
\begin{align*}
& f_{, t}=\bar{B}\left(\frac{\delta H}{\delta f}\right)  \tag{15}\\
& \bar{B}:=\sum \frac{\varepsilon^{r}}{r!}\left[\partial^{r} f\left(p \partial_{p}\right)^{r}-\left(\partial_{p} p\right) f \partial^{r}\right] . \tag{16}
\end{align*}
$$

Then the matrix $\bar{B}(16)$ is Hamiltonian.
Property 3. If $H$ in (15) depends upon $f$ only through the $a$, the Hamiltonian system (15) implies the Hamiltonian system (14). In other words, the moments map (9) is a canonical (=Hamiltonian) map between the Hamiltonian structures (16) and (13).

Corollary 1. For $Q=L^{m}, m \in \mathbf{Z}_{+}$, the kinetic representation (11) is the same as (15) with $H=\operatorname{Res}\left(L^{m+1}\right) /(m+1)$, where

$$
\begin{equation*}
\operatorname{Res}\left(\sum \varphi_{\xi^{\prime}}\right):=\varphi_{0} \tag{17}
\end{equation*}
$$

Indeed, the moments map (9) is injective, and the system (1) can be put into the Hamiltonian form (14) with the Hamiltonian $H=\operatorname{Res}\left(L^{m+1}\right) /(m+1)[1,2]$.

Corollary 2. When $H$ runs through the set $\left\{\operatorname{Res}\left(L^{m+1}\right) /(m+1) \mid m \in \mathbb{Z}_{+}\right\}$, the kinetic flows (15) all commute.

Indeed, this set of Hamiltonians is in involution with respect to the Hamiltonian structure $B$ (13) since the Hamiltonian flows (1) all commute [1,2]; by property 3, the moments map (9) is canonical; hence, these Hamiltonians are in involution in the Hamiltonian structure (16); therefore, the kinetic flows (15) commute as well.

Proof of 1. Equations (10) and (11) are, in full,

$$
\begin{align*}
& a_{i, t}=\sum\left[\Delta^{j}\left(a_{i+j}\right) q_{j}-a_{i+j} \Delta^{-i-j}\left(q_{j}\right)\right]  \tag{18}\\
& f_{, 1}=\sum p^{j} \Delta^{j}(f) q_{j}-\sum \frac{\varepsilon^{r}}{r!} p^{j}\left(\partial_{p} p\right)^{r}(f) \partial^{r}\left(q_{j}\right) . \tag{19}
\end{align*}
$$

Applying to (19) the operation $\int_{-\infty}^{\infty} p^{i} \mathrm{~d} p$ and using the formula

$$
\begin{equation*}
\int_{-\infty}^{\infty} p^{i}\left(\partial_{p} p\right)^{r}\left(f p^{j}\right) \mathrm{d} p=(-\mathrm{i})^{r} a_{i+j} \tag{20}
\end{equation*}
$$

we obtain (18).
Proof of 2. The multiplication of symbols of pseudodifferential operators is an associative operation given by the formula [3]

$$
\varphi \circ \psi=\sum_{r} \frac{1}{r!} \partial_{\xi}^{r}(\varphi) \partial^{r}(\psi)
$$

for functions of $x$ and $\xi$. Changing $\xi$ into $p=\exp (-\varepsilon \xi)$ results in the multiplication

$$
\varphi \circ \psi=\sum \frac{(-\varepsilon)^{r}}{r!}\left(p \partial_{p}\right)^{r}(\varphi) \partial^{r}(\psi)
$$

which produces the Lie algebra structure
$[\varphi, \psi]_{(2)}:=\psi \circ \varphi-\varphi \circ \psi=\sum \frac{(-\varepsilon)^{r}}{r!}\left[\partial^{r}(\varphi)\left(p \partial_{p}\right)^{r}(\psi)-\left(p \partial_{p}\right)^{r}(\varphi) \partial^{r}(\psi)\right]$.
Denoting by $f$ the coordinate on the dual space to the Lie algebra $g$ with the commutator (21), we compute the associated Hamiltonian matrix $\bar{B}:=B(\mathrm{~g})$ by the standard rule [2]:

$$
\varphi \bar{B}(\psi) \sim f[\varphi, \psi]_{(2)}
$$

which yields (16).
Proof of 3. If $H$ depends upon $f$ only through the $a$ then

$$
\frac{\delta H}{\delta f}=\sum p^{k} H_{k}
$$

and (15) becomes

$$
\begin{align*}
f_{, t} & \left.=\sum \frac{\varepsilon^{r}}{r!}\left[\partial^{r} f\left(p \partial_{p}\right)^{r}-\left(\partial_{p} p\right)^{r} f \partial^{r}\right)\right]\left(p^{k} H_{k}\right) \\
& =\sum \frac{\varepsilon^{r}}{r!}\left[\partial^{r}\left(f H_{k}\right) k^{r} p^{k}-\left(\partial_{p} p\right)^{r}\left(f p^{k}\right) \partial^{r}\left(H_{k}\right)\right] \\
& =\sum \Delta^{k}\left(f H_{k}\right) p^{k}-\sum \frac{\varepsilon^{r}}{r!}\left(\partial_{p} p\right)^{r}\left(f p^{k}\right) \partial^{r}\left(H_{k}\right) . \tag{22}
\end{align*}
$$

Applying to (22) the operation $\int_{-\infty}^{\infty} p^{i} \mathrm{~d} p$ and using formula (20) we get (14).
Taking the continuous limit of the properties 1-3 yields the corresponding properties of the continuous zero-dispersion hierarchy commuting with (7).

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